

## **METHOD AND SYSTEM FOR AUTOMATED CONFIGURING OF A HART MULTI-DROP SYSTEM**

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### **TECHNICAL FIELD**

The present invention relates to a method of automatically configuring a so-called HART multidrop system, comprising a master device and a plurality of slave devices connected to the at least one master device. Moreover, the present invention relates to a HART multidrop system customized for the implementation of the method according to the present invention.

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### **BACKGROUND OF THE INVENTION**

A HART multidrop system basically consists of one or two master devices and a plurality of slave devices connected to the at least one master device. The slave devices are also referred to as field devices and can comprise various sensors, actuators or other devices, such as a handheld device. In particular, such slave devices are filling level sensors, pressure or 15 temperature sensors or flow-through sensors.

The slave devices are connected to the at least one master device through a so-called 4 to 20 mA two-wire loop. The communication between the master device and the slave devices is carried out using the well-known HART protocol. Regarding the HART protocol, particular reference is made to the publication "HART-field Communications Protocol, A Technical 20 Overview (Second Edition), Romilly Bowden, September 2003, Emerson Process Management". This specification of the HART protocol is sold by Fisher-Rosemount Ltd. and is generally commercially available.

In a HART multidrop system, a master device usually takes care of the energy supply of the slave devices, and communication with the connected slave devices is carried out through the 25 master device. Slave devices for a HART system are usually adapted in such a way that they can be operated with a maximum feed current of 20 mA. This is the maximum current which can be supplied by a master device when the communication between the master device and a slave device is analog, i.e. when the current fed by the slave device into the two-wire loop is

proportional to the measured signal. When there is a plurality of slave devices, the communication with the master device is digital. Herein the feeding current is reduced to 4 mA. The slave devices thus have a first mode in which they are in analog communication with the master device and a second mode (multidrop mode) in which they communicate 5 digitally with the master device and wherein the operation is such that each slave device is operable with a feeding current of 4 mA.

In conventional HART multidrop systems, each slave device has to be switched over to the multidrop mode on site by the operator. This can be particularly troublesome when the several 10 slave devices are at a particularly great distance from the master device or when the slave devices are placed at great distances to each other. In a production process, for example, the filling levels, temperatures and pressures may have to be checked in various storage tanks, wherein the storage tanks may be positioned, however, at several tens or hundreds of meters or more from each other. In order to configure such a HART multidrop system, an operator must connect each individual slave device to the system and switch it over to the multidrop 15 mode on site. This time-consuming process must also be carried out before the HART multidrop system is put into operation.

## SUMMARY OF THE INVENTION

According to a first aspect of the present invention, a method of automatically configuring a HART multidrop system consisting of at least one master device and a plurality of slave 20 devices, comprises the following process steps. According to this first aspect of the present invention, a system is newly created: the slave devices are connected to the multidrop system. Once the slave devices are connected to the master device, the power source present in the master device for the supply of the slave devices is switched on. At the same time or after 25 this, HART command No. 6 "write polling address" is sent as a broadcast command. By sending command No. 6 as a broadcast command, all slave devices in the HART multidrop system are addressed and switched into the multidrop mode. As an address for the slave devices, a polling address not equal to 0 (i.e., according to the present state of the art, integer values between 1 and 15, as specified by the HART protocol) is assigned by command No. 6. As a result, all slave devices have now assumed the multidrop mode, but they all have the

same address. Then it has to be ensured that each of the slave devices present in the HART multidrop system obtains a unique address and a unique identifier. This can be done in either of two ways, which will be explained below.

According to a second aspect of the present invention, an existing HART multidrop system

5 comprising one or more slave devices is complemented by at least one more slave device. For this purpose, at least one additional slave device is connected to the existing HART multidrop system. Once all slave devices are connected, the power source present in the master device is switched off, if indeed it is still switched on, and then it is switched on again, as soon as the slave devices are isolated from the voltage or the current. At the same time or after this, the  
10 HART command No. 6 "write polling address" is sent as a broadcast command. By sending command No. 6 as a broadcast command, all slave devices of the HART multidrop system are addressed and switched into multidrop mode. As an address for the slave devices, a polling address not equal to 0 (i.e., according to the present state of the art, integer values between 1 and 15, as specified by the HART protocol) is assigned by command No. 6. With this, all  
15 slave devices have now assumed the multidrop mode, but they all have the same address. Then it has to be ensured that each of the slave devices present in the HART multidrop system obtains a unique address and a unique identifier.

The assignment of a unique polling address and/or a unique identifier can be carried out, for example, as follows. For example, the unique identifier for a slave device is queried via a

20 programmed routine, which the operator can then enter manually, and a polling address is also queried (a number between 1 and 15), which the operator has to input. As a modification it is also possible for the polling address to be automatically assigned after the identifier is input, which means that the operation does not need to enter a corresponding polling address. Then command No. 6 with the long frame address corresponding to the input identifier is  
25 transmitted together with the now determined polling address of the slave device. The slave device, which is now uniquely addressed by the long frame address, thus obtains the new assigned polling address. This process is repeated for all connected slave devices. Finally, all slave devices have a determined address (1 to 15) and are individually addressable by the master device through the unique identifier.

Alternatively, the whole process can be partially or wholly automated. For this purpose, the unique identifier for each connected slave device is automatically taken from a previously determined database and the polling address is automatically assigned. The long frame address created in this manner and command No. 6 with the polling address determined for a 5 certain slave device are thus automatically transmitted. In other words: the system checks which slave devices are connected to the multidrop system and automatically assigns a specific address for each of the slave devices, which can be a number between 1 and 15 (as presently specified by the HART protocol). If an address, such as 2, has already been assigned, an address which has not yet been assigned, is automatically assigned, in particular, 10 the next higher address. Finally, all slave devices connected to the master device have now obtained their unique polling addresses and are individually recognizable.

For more detail on how automatic processes for the assignment of addresses can be carried out, reference is made to DE 102 02 851 A1 (US 2003140125 or EP 1331794) to avoid undue repetition. Here, an example of a method of assigning addresses in a network component is 15 explained in detail. Moreover, other well-known automatic address assignment techniques may also be used in the present HART multidrop system.

Due to the fact that according to the present state of the art, HART communication is relatively slow, the above explained semi-automatic address assignment method is preferred over the above explained fully automatic address assignment method.

20 In another exemplary embodiment of the present invention, it is checked before the power source is turned on again in the master device to supply the slave devices, whether the slave devices are indeed without voltage or current. In other words, it is checked whether the supply voltage or the supply current in the master device for the supply of the slave devices is about 0, i.e. that the current is < 4 mA or < 3.6 mA in particular.

25 Alternatively, the renewed switching on of the power source can take place after a predetermined time interval after the power source has been turned off. The time interval is chosen in such a way that it is ensured that before the power source for the slave devices is turned on again, no voltage is applied or no appreciable current is available.

In another exemplary embodiment of the present invention, for reassigning an address to the slave devices after their switch-over into the multidrop mode, a unique address of between 1 and 15 can be inputted for each slave device by the operator. The unique address for each slave device can be obtained by way of an inquiry, or obtained from a database.

5 Another exemplary embodiment of the present invention provides that before the unique address for a slave device is input it is queried whether the slave device has been configured before, and if so, the same address of this slave device is assigned again. Thus, if the unique identifier of a slave device and the address (a value between 1 and 15) are known, they are transmitted in a long frame address with HART command No. 6 so that a slave device  
10 uniquely identified by the unique identifier now also obtains its own polling address.

The unique identifier for a slave device can be the serial number of the slave device and the manufacturer ID code and a so-called device type code. With these three features, a unique long frame address can be formed, and therefore a single slave device can be directly addressed. By using HART command No. 6 into which this unique long frame address is  
15 integrated, a unique polling address (1 – 15) can be assigned to that specific slave device which is different from the identical address (polling address) that was the same for all slave devices.

According to another aspect of the present invention, a HART multidrop system comprises at least one master device which has a power source to supply the slave devices, and a plurality  
20 of slave devices connected to the at least one master device. Moreover, a control unit is also present which for the purpose of automatically configuring the HART multidrop system switches off the power source of the master device, if it is still switched on when the slave devices are connected, and which hereafter switches back on again the power source in the master device for the supply of the slave devices. The control unit, after the renewed  
25 switching on, sends the HART command "write polling address" as a broadcast command with a polling address not equal to zero, which causes all slave devices connected to the master device to be automatically switched over to the multidrop mode. All slave devices thus obtain the identical address not equal to zero. The control unit also has the function of changing the identical address of all slave devices caused by the transmission of the above

broadcast command into a unique address for each slave device, either fully automatically or in an inquiry routine in combination with an operator input. For this purpose, advantageously an input unit is present for the operator. It is also advantageous if a display unit is present, on which the values or data to be input by the operator are inquired after.

## 5 SHORT DESCRIPTION OF THE DRAWINGS

For further explanation and for better understanding, several exemplary embodiments of the present invention are described below with reference to the accompanying drawings, in which:

Fig. 1 shows a basic structure of a HART multidrop system;

10 Fig. 2a shows a first part of a flow diagram of a process routine with the aid of which the slave devices in a HART multidrop system are automatically switched over to the multidrop mode;

Fig. 2b shows a flow chart of a process routine showing an option to assign addresses to already configured sensors after the switchover into the multidrop mode;

15 Fig. 2c shows another flow chart of a process routine to assign addresses to not yet  
configured sensors and to assign them to a measuring position;

Fig. 3 illustrates dialog 1 mentioned in Fig. 2 as displayed on a display unit to an operator (such as on the master device);

Fig. 4 illustrates dialog 2 mentioned in Fig. 2 as displayed on a display unit to an operator;

20 Fig. 5 illustrates dialog 3 mentioned in Fig. 2 as displayed on a display unit to an operator;

Fig. 6 illustrates dialog 4 mentioned in Fig. 2 as displayed on a display unit to an operator;

Fig. 7 illustrates dialog 5 mentioned in Fig. 2 as displayed on a display unit to an operator;

Fig. 8 illustrates dialog 6 mentioned in Fig. 2 as displayed on a display unit to an operator on the master device;

Fig. 9 illustrates dialog 7 mentioned in Fig. 2 as displayed on a display unit to an operator on the master device;

5 Fig. 10 illustrates dialog 8 mentioned in Fig. 2 as displayed on a display unit to an operator on the master device.

## **DESCRIPTION OF EXEMPLARY EMBODIMENTS OF THE INVENTION**

With reference to Fig. 1, the basic structure of a HART multidrop system is shown. The HART multidrop system comprises a master device 1, to which a plurality of slave devices 2<sub>1</sub> ... 2<sub>15</sub> may be connected via a two-wire line 4. Master device 1 communicates with slave devices 2<sub>1</sub> ... 2<sub>15</sub> via the two-wire loop 4 and supplies energy to them. The communication between master device 1 and slave devices 2<sub>1</sub> ... 2<sub>15</sub> is carried out using commands known from the HART protocol. Slave devices 2<sub>1</sub> ... 2<sub>15</sub> in turn, again using the HART protocol, send information to master device 1 when they are addressed.

15 For the communication between master device 1 and a specific slave device 2<sub>1</sub> ... 2<sub>15</sub>, each slave device 2<sub>1</sub> ... 2<sub>15</sub> has both a unique identifier and a specific address (polling address). The unique identifier can consist of the serial number and/or the manufacturer ID code and/or the device type code. Other characterizing features of a slave device 2<sub>1</sub> ... 2<sub>15</sub> may, of course, also be used for unique identification. A unique long frame address is then formed using these 20 features, which serve to address a specific slave device 2<sub>1</sub> ... 2<sub>15</sub>. The so-called polling address is a number between 1 and 15. A polling address 0 means that the device is not in the multidrop mode.

As shown in Fig. 1, master device 1 comprises a power source 3 used to supply energy to the slave devices. In the exemplary embodiment shown here, an input and display unit 5 is 25 connected to master device 1. However, it is also possible not to connect input and display

unit 5 to master device 1, but at any place on wire line 4. For more details of the input and display unit, reference is made to the explanations below.

Figs. 2a to 2c show the basic flow charts which illustrate the basic sequence of the method according to the present invention or of parts thereof. In the flow chart shown in Fig. 2a, the

- 5 various slave devices  $2_1 \dots 2_{15}$  are switched over to the multidrop mode and all set to the same address (polling address). The sensor supply 3 in master device 1 is switched off in step 10. In step 11 it is checked whether the current for the slave devices  $2_1 \dots 2_{15}$  is 0 mA. Alternatively it may also be checked whether the voltage is 0 Volts. If it is determined that the current or voltage is not about 0 mA or 0 Volts, respectively, the sensor supply is not
- 10 switched back on, otherwise the power source 3 in master device 1 is turned on again in step 12. Then it is checked in an optional step 13 whether there is a short circuit or whether the current in the two-wire loop 4 is less than 3.6 mA. If the answer to either is yes, an error message 14 is output. The error message can be seen on the display and input unit 5 according to Figs. 3 or 4.
- 15 If there is no short circuit or if the current is greater than 3.6 mA, step 15 is next. The slave devices  $2_1 \dots 2_{15}$  are set to the polling address 15 by HART command No. 6 as a broadcast command. By transmitting command No. 6 as a broadcast command with a polling address not equal to zero, all slave devices are addressed via this command and obtain the same polling address 15.
- 20 In optional step 16 it is determined whether the current in the two wire line 4 is a multiple of 4 mA. If this is not the case, it is determined in step 17 whether the measured current is not equal to 0 mA. If the answer is yes, step 15 is repeated. If this is not the case, the output in step 18 is that no sensor is connected. The corresponding dialog is shown on the input and display unit 5 according to Fig. 3.
- 25 If it is determined in step 16 that the measured current is indeed a multiple of 4 mA, the number of connected slave devices is determined in step 19 by dividing the measured current by 4 mA.

With this, the basic sequence of process steps for the automatic operation of a plurality of slave devices  $2_1 \dots 2_{15}$  in a HART multidrop system is complete, with all slave devices  $2_1 \dots 2_{15}$  still having polling address 15, however.

In the optional routine shown in the flow diagram according to Fig. 2b, it is checked whether

5 already configured sensors exist and whether these configured sensors have to be given new addresses. For this purpose, a counter  $n$  is set to the value 1 in step 20. It is checked in step 21 whether the value is greater than 15. If this is not the case, the measuring place having value  $n$  is checked in step 22 as to whether it is already configured. If so, HART command No. 6 with the long frame address is determined in step 22, wherein the measuring place having the value 10  $n$  is set to the HART address of measuring place  $n$ . Then value  $n$  is incremented by 1 in step 24. This loop is cycled through until all configured measuring places have been recorded. This means that loop 21 is interrupted as soon as value  $n$  is greater than 15.

Fig. 2c illustrates the addressing of the slave devices  $2_1 \dots 2_{15}$  which have not been given a unique polling address before. It is determined in step 25 whether there are still slave devices

15 having the address 15. If this is not the case, the sensor addressing is completed according to step 25 and normal operation of the HART multidrop system is initiated. If there are still slave devices  $2_1 \dots 2_{15}$  with an address 15, the operator is prompted in step 27 to input the serial number and the desired polling address for the slave device. The corresponding dialog is shown in Fig. 5. Then in step 28 the selection of the sensor assignment is carried out. The 20 corresponding dialog which is displayed on the display and input unit 5 is shown in Fig. 7.

In step 26 it is checked whether only one slave device remains which has not yet been assigned a unique polling address. If the result of this checking is that only one slave device still has the polling address which was assigned to all slave devices, the routine according to the dialog 4, i.e. Fig. 6, can be completed. According to this dialog, the user can assign a not

25 yet assigned address to the remaining slave device or it leaves the already assigned polling address. This last slave device does not necessarily have to obtain a unique identifier like the others according to the description below.

The operation follows step 29 if no selection is to be made. The operation follows step 30 if the measuring place is free. If the measuring place has already been configured, the measuring place is overwritten in step 31. If further measuring places are to be assigned to a slave device, the corresponding inquiry is carried out in step 33. The corresponding dialog is shown 5 in Fig. 10. This loop is cycled through until all measuring places have been configured and all slave devices  $2_1 \dots 2_{15}$  have their unique addresses and their unique identifiers. Then each slave device can be uniquely addressed in the multidrop operation. For further detail, reference is made to the HART protocol.